

What is a
Moduli Problem?

Andrew Kobin (UC Santa Cruz)

akobin@ucsc.edu / andrewkobin.com



Begonia



Poppy

Today's lesson plan:



Individual
objects



Points
of a
moduli space

*By the way, I just finished
grad school last year.*





Ha ha as if I ever looked that
good! It was more like:

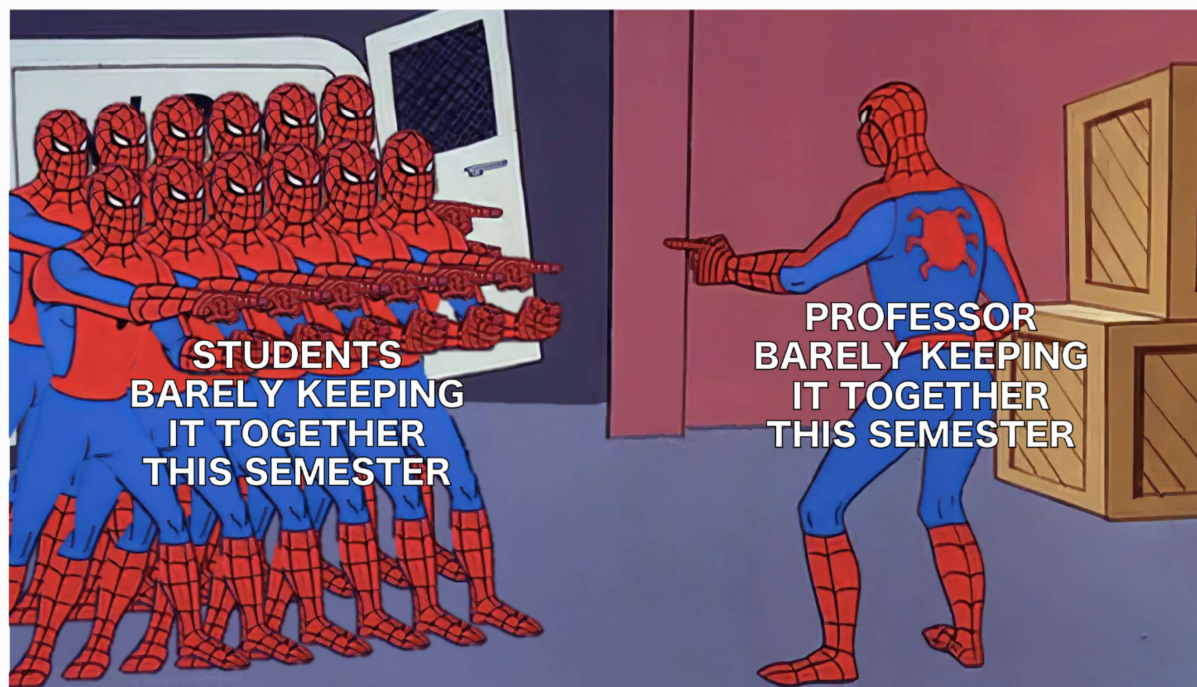


me c. 2015



me 2020 (-present)

Okay one more (for now):



Introduction

Loose definition: a moduli problem
is a problem of the form

"... consist of all objects of a certain type"

classifying all objects

usually + "up to equivalence"

In many situations, the solutions to such problems can be parametrized geometrically — we can view the solutions themselves as points in some parameter space, called a moduli space.



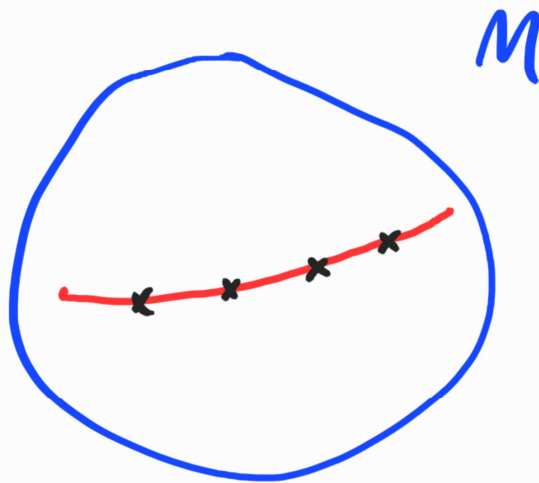
The utility of this is:

- if the space M has any extra structure (e.g. a metric, a group structure, the structure of a variety), then this sheds light on all solutions simultaneously,
- most powerfully, we can produce families of solutions by picking meaningful subsets

of the moduli space.

sol'n
sol'n
sol'n
sol'n

family of
solutions
parametrized
by a curve



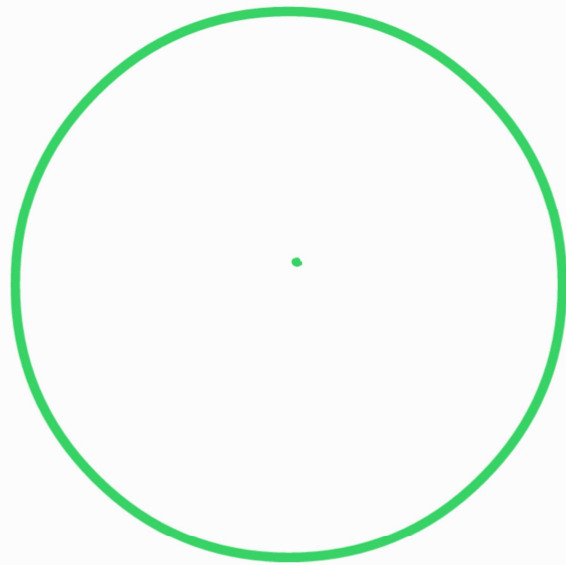
Elementary Examples

Here are some familiar examples:

① Circles in \mathbb{R}^2 $(x-h)^2 + (y-k)^2 = r^2$
 (h, k) , r

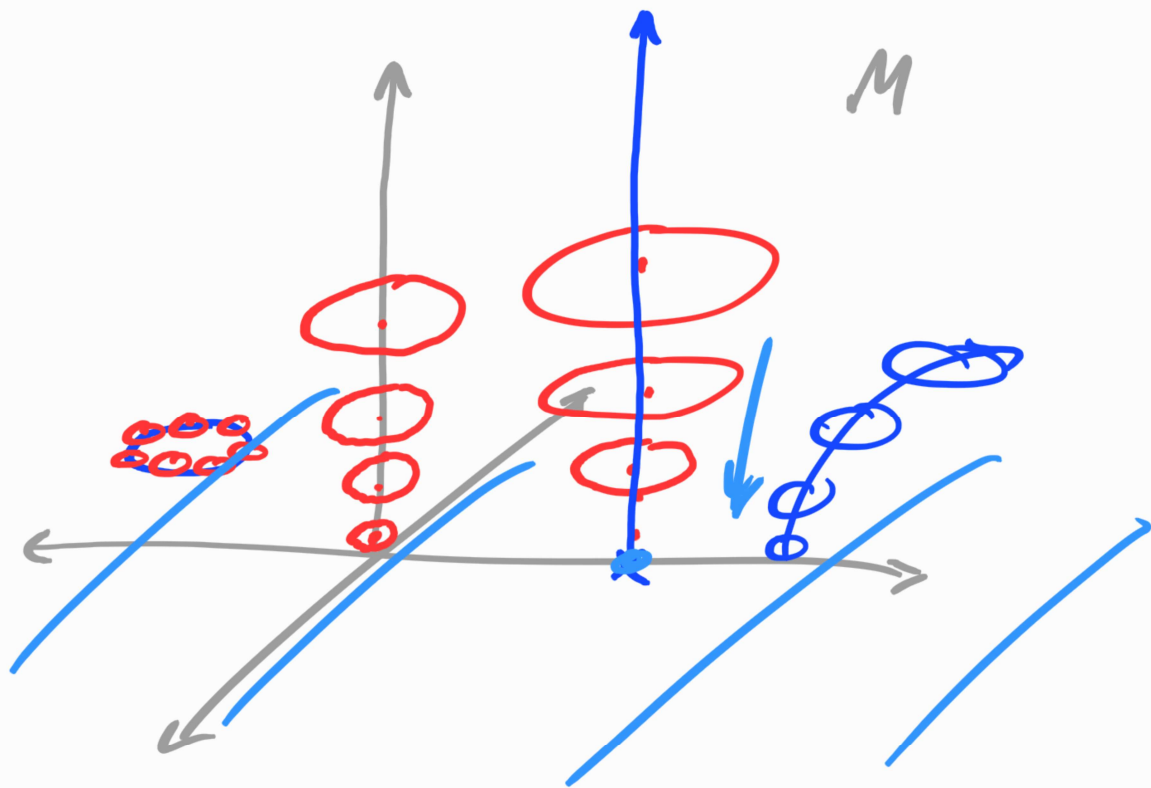
Every circle $C \subseteq \mathbb{R}^2$ is uniquely

specified by center + radius.



A moduli space for circles in \mathbb{R}^2

is $\mathbb{R}^2 \times \mathbb{R}_{>0} = \mathbb{R}^2 \times (0, \infty)$
center radius



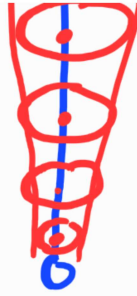
② Circles in \mathbb{R}^2 up to isometry

Two circles $C_1, C_2 \subseteq \mathbb{R}^2$ are isometric if they have the same size.

So circles up to isometry are classified by radius.

A moduli space for circles up to isometry is





all radius
= circles



(3) Lines in \mathbb{R}^2

A line in \mathbb{R}^2 is given by an equation $ax + by = c$, so we can think of

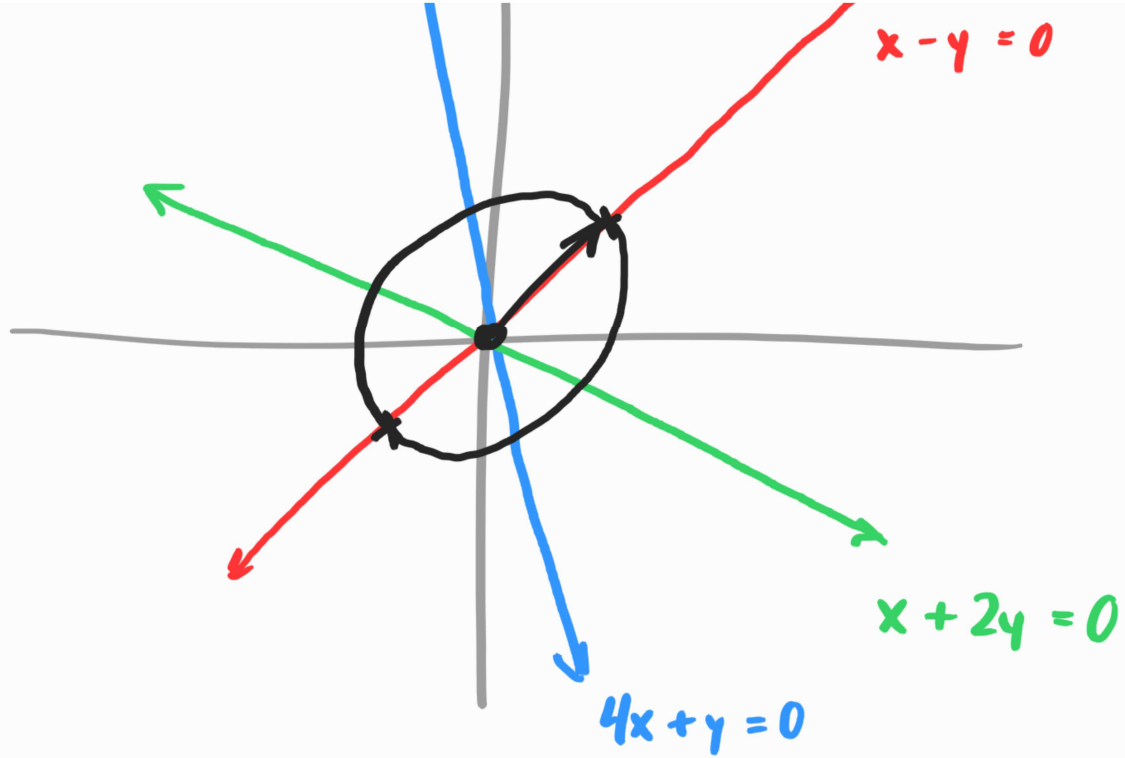
$$\mathbb{R}^3 = \{(a, b, c) \mid a, b, c \in \mathbb{R}\}.$$

BUT this misses when two equations represent the same line

$$\text{e.g. } (x + y = 1) \simeq (2x + 2y = 2)$$

To make things simpler, let's just consider lines through $(0, 0)$:





$$L: ax + by = 0$$

A line through the origin is
uniquely specified by

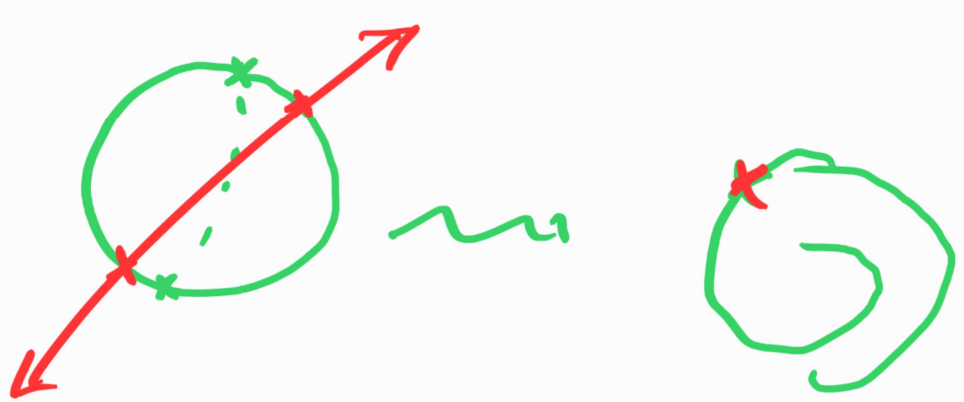
$$ax + by = 0 \quad \rightsquigarrow \quad \text{slope} \quad -\frac{a}{b}$$

pick (x, y) on S' up to

± 1

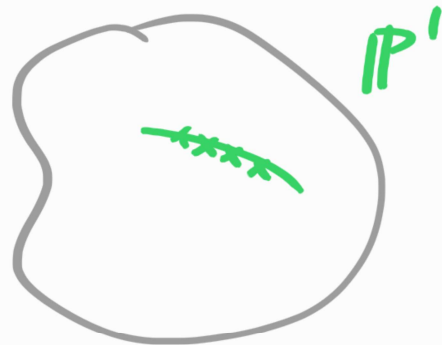
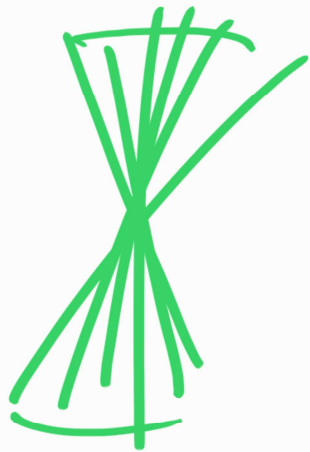
A moduli space of lines through
the origin is

$S^1/\sim =$ pts. on circle
up to
being antipodes



$$S^1/\sim = \mathbb{P}^1$$

projective line



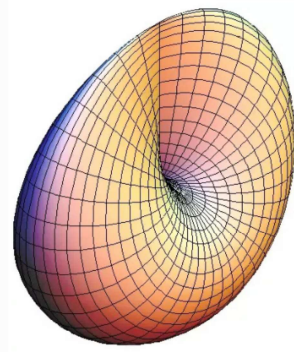
④ More generally,

$$\left\{ \begin{array}{l} \text{lines through} \\ \vec{0} \text{ in } \mathbb{R}^n \end{array} \right\} \longleftrightarrow \left\{ \begin{array}{l} \text{unit vector} \\ \text{up to } \pm 1 \end{array} \right\}$$



$$\left\{ \begin{array}{l} \text{points in} \\ \mathbb{P}^{n-1} \end{array} \right\}$$

where $\mathbb{P}^{n-1} = S^{n-1} / \text{identify antipodes}$



IP^{n-1}

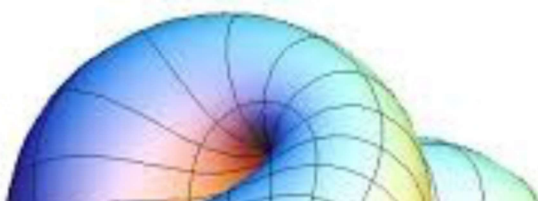
Most generally,

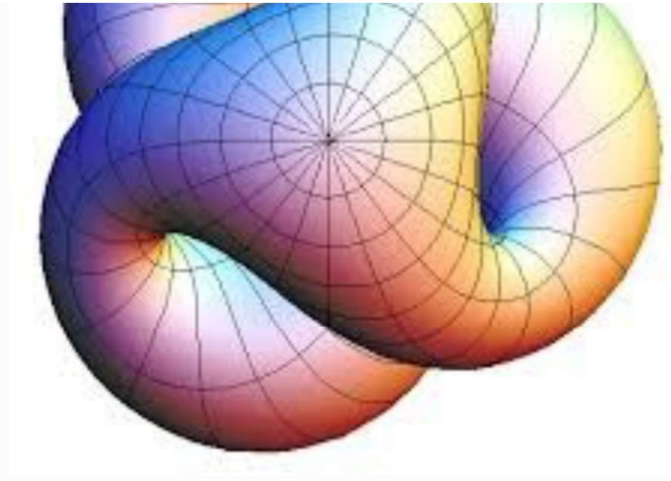
$$\left\{ \begin{array}{l} k\text{-dim'l subspaces} \\ \text{in } \mathbb{R}^n \end{array} \right\} \longleftrightarrow \left\{ \begin{array}{l} k\text{-frame} \\ \text{up to} \\ GL_k(\mathbb{R}) \end{array} \right\}$$



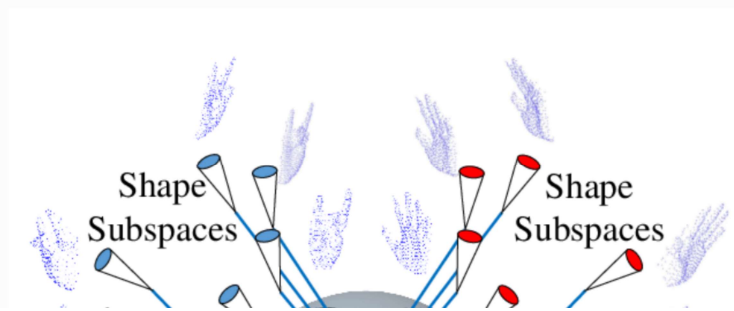
$$\left\{ \begin{array}{l} \text{points in} \\ Gr(k, n) \end{array} \right\}$$

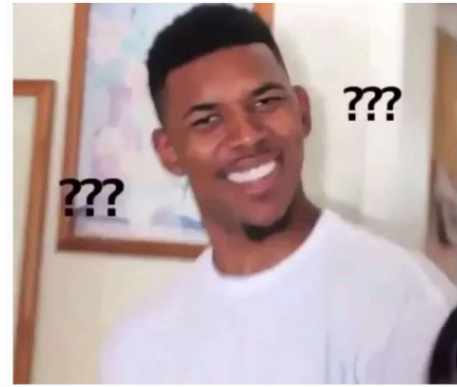
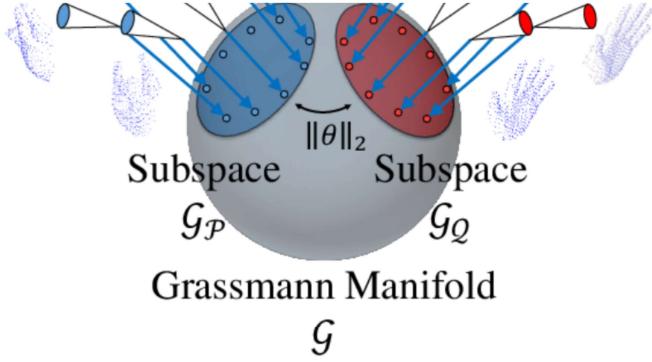
where $Gr(k, n) =$ Grassmannian manifold.





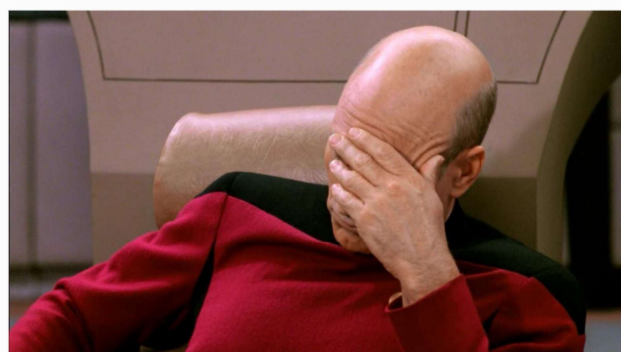
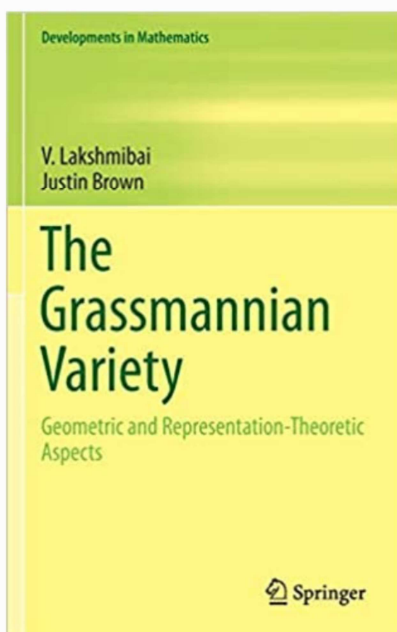
Just kidding, I couldn't find
any good pics of a Grassmannian
manifold ...





Google searched
 "Grassmannian manifold"

Apparently algebraic geometers are
 even less imaginative :



Google searched
"Grassmannian
variety"

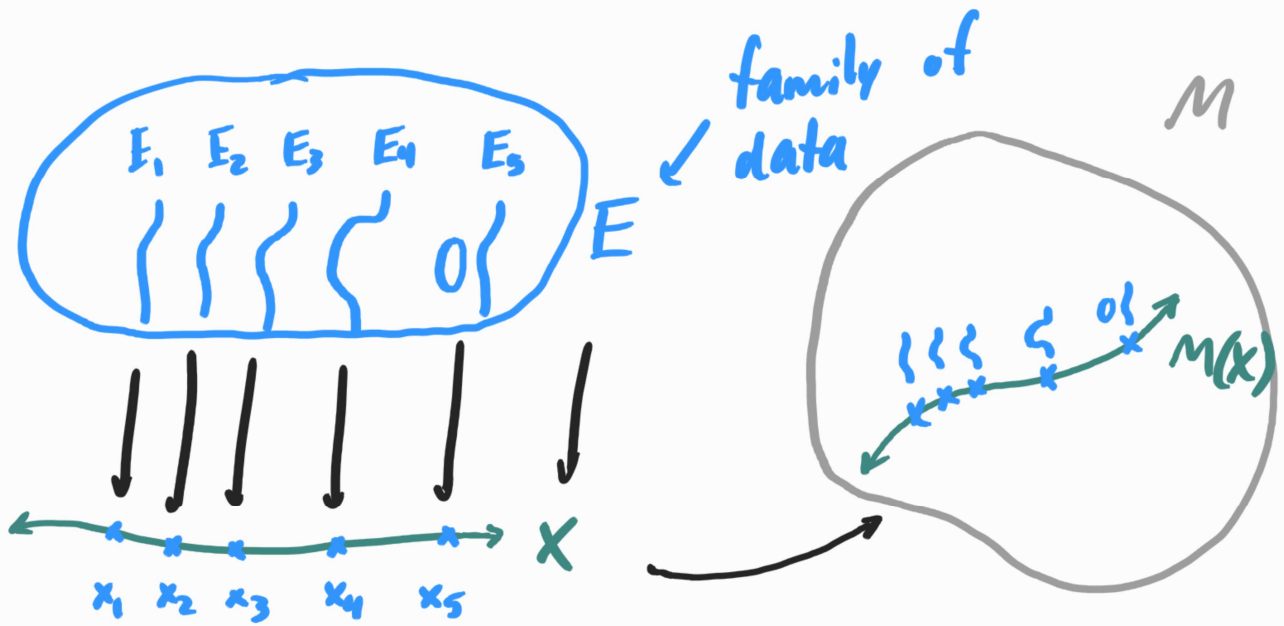
Modern Theory

Let M be a moduli space, so
that points of M correspond to
some interesting information we'd
like to keep track of.

e.g. $M = \mathbb{P}^1 \leftrightarrow$ lines through the
origin in \mathbb{R}^2

The real power of M is that
it helps us parametrize families

of such information:



Slogan: it's all about the arrows.

If $f: Y \rightarrow X$ is a function

between spaces (that's continuous,

between spaces

differentiable, holomorphic, linear,
a homomorphism, etc.) then
we can use f to transfer
information from X over to Y .

