

What is ...
a Moduli Space?

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Begonia



Poppy

Today's lesson plan:



Individual
objects



Points
of a
moduli space

Introduction

Loose definition: a moduli problem
is a problem of the form

"classify all objects of a certain type"

usually + "up to isomorphism"

In many situations, the solutions to such problems can be parametrized geometrically — we can view the solutions themselves as points in some parameter space, called a **moduli space**.

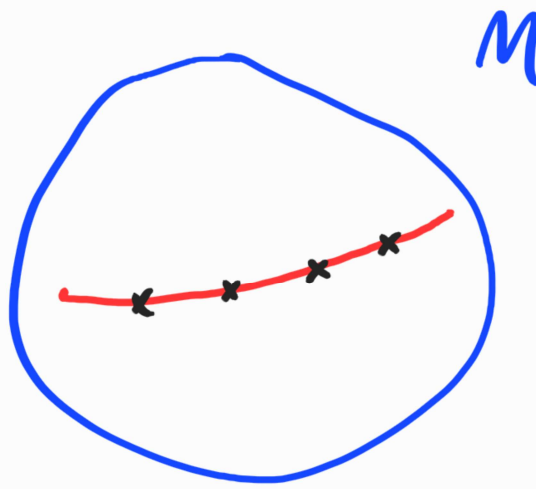


The utility of this is:

- if the space M has any extra structure (e.g. a metric, a group structure, the structure of a variety), then this sheds light on all solutions simultaneously,
- most powerfully, we can produce families of solutions by picking meaningful subsets of the moduli space.

sol'n
sol'n
sol'n
sol'n

family of
solutions
parametrized
by a curve



Here are some familiar examples:

① Circles in \mathbb{R}^2

Every circle $C \subseteq \mathbb{R}^2$ is uniquely

specified by center + radius.



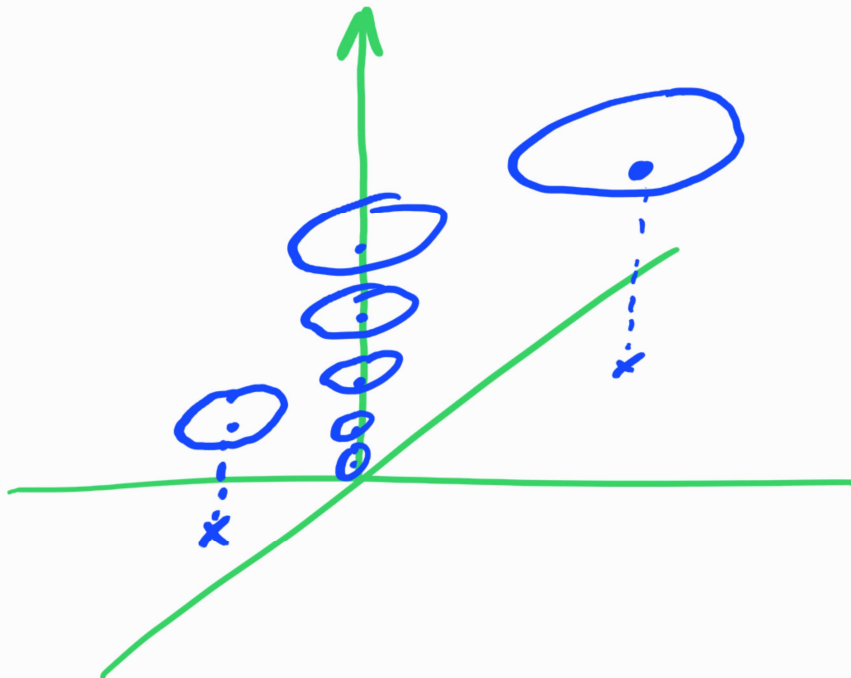
$$(x, y) \in \mathbb{R}^2$$

$$r \in (0, \infty)$$

A moduli space for circles in \mathbb{R}^2

is

$$\mathbb{R}^2 \times \mathbb{R}_{>0}$$

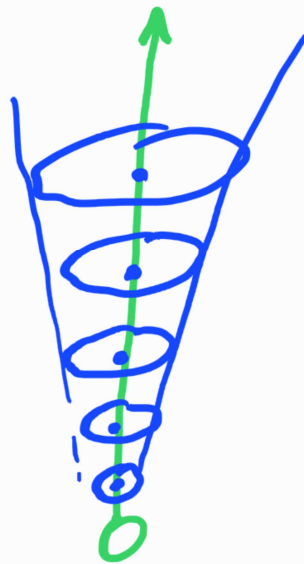


② Circles in \mathbb{R}^2 up to isometry

Two circles $C_1, C_2 \subseteq \mathbb{R}^2$ are
isometric if they have the
same size.

So circles up to isometry are
classified by radius.

A moduli space for circles up
to isometry is $\mathbb{R}_{>0}$



③ Lines in \mathbb{R}^2

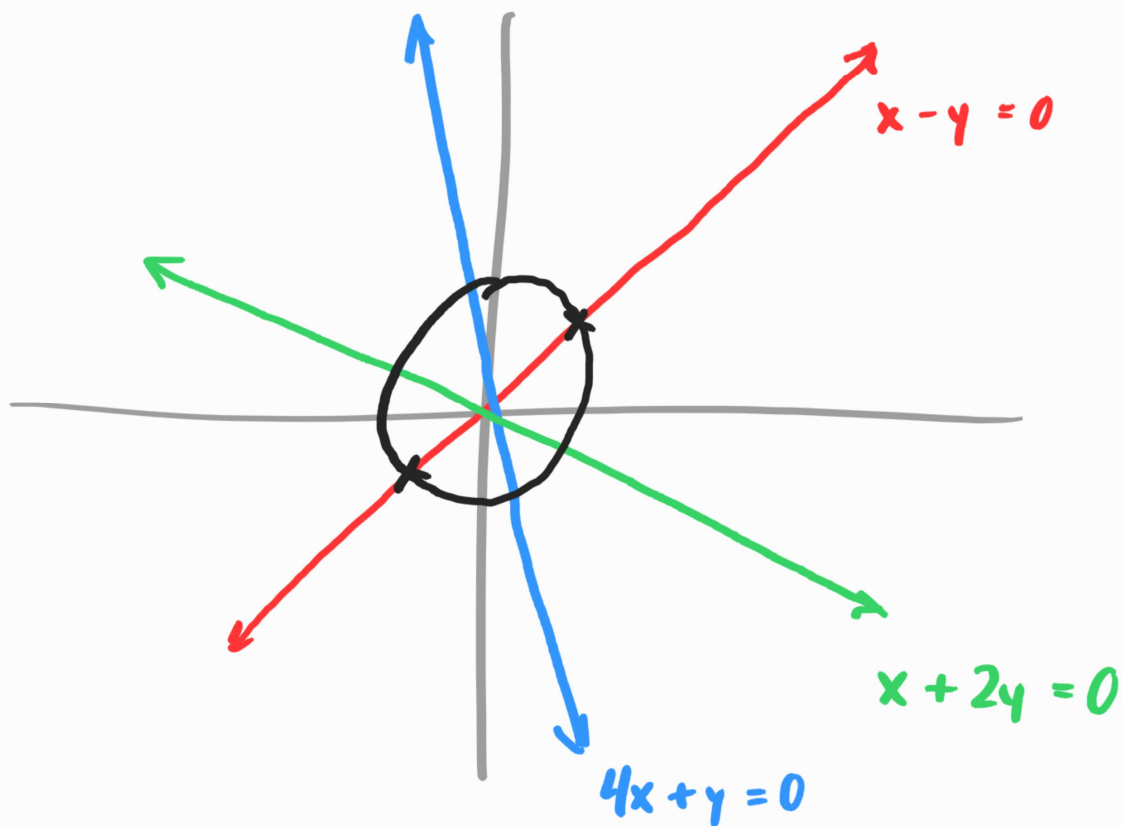
A line in \mathbb{R}^2 is given by an equation $ax + by = c$, so we can think of

$$\mathbb{R}^3 = \{ (a, b, c) \mid a, b, c \in \mathbb{R} \}.$$

BUT this misses when two equations represent the same line

$$\text{e.g. } (x + y = 1) \simeq (2x + 2y = 2)$$

To make things simpler, let's
just consider lines through $(0, 0)$:



$$L: ax + by = 0$$

A line through the origin is

uniquely specified by

✓ slope = $-\frac{a}{b} \in \mathbb{R}$

✓ any point in $\mathbb{R}^2 \setminus \{0\}$ up to
scaling (\mathbb{R}^\times)

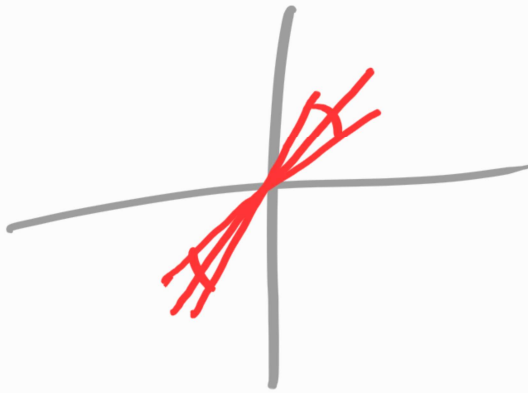
✓ a point on $C = \{x^2 + y^2 = 1\}$
up to ± 1

A moduli space of lines through
the origin is

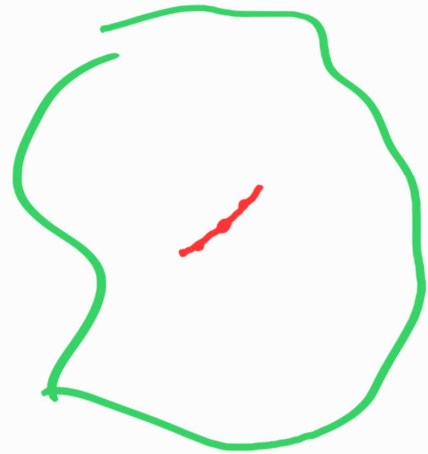
$$\mathbb{P}^1 = C / \sim \quad \text{where}$$

$$x \sim -x$$

"projective line"



\mathbb{P}^1



④ More generally,

$\left\{ \begin{array}{l} \text{lines through} \\ \vec{n} \text{ in } \mathbb{R}^n \end{array} \right\} \longleftrightarrow \left\{ \begin{array}{l} \text{unit vector} \\ \text{up to } \pm 1 \end{array} \right\}$

↕

{ points in
 \mathbb{P}^{n-1} }

where $\mathbb{P}^{n-1} = S^{n-1} / \text{identify antipodes}$

Most generally,

{ k-dim'l subspaces
in \mathbb{R}^n } ↔ { k-frame
up to
 $GL_k(\mathbb{R})$ }

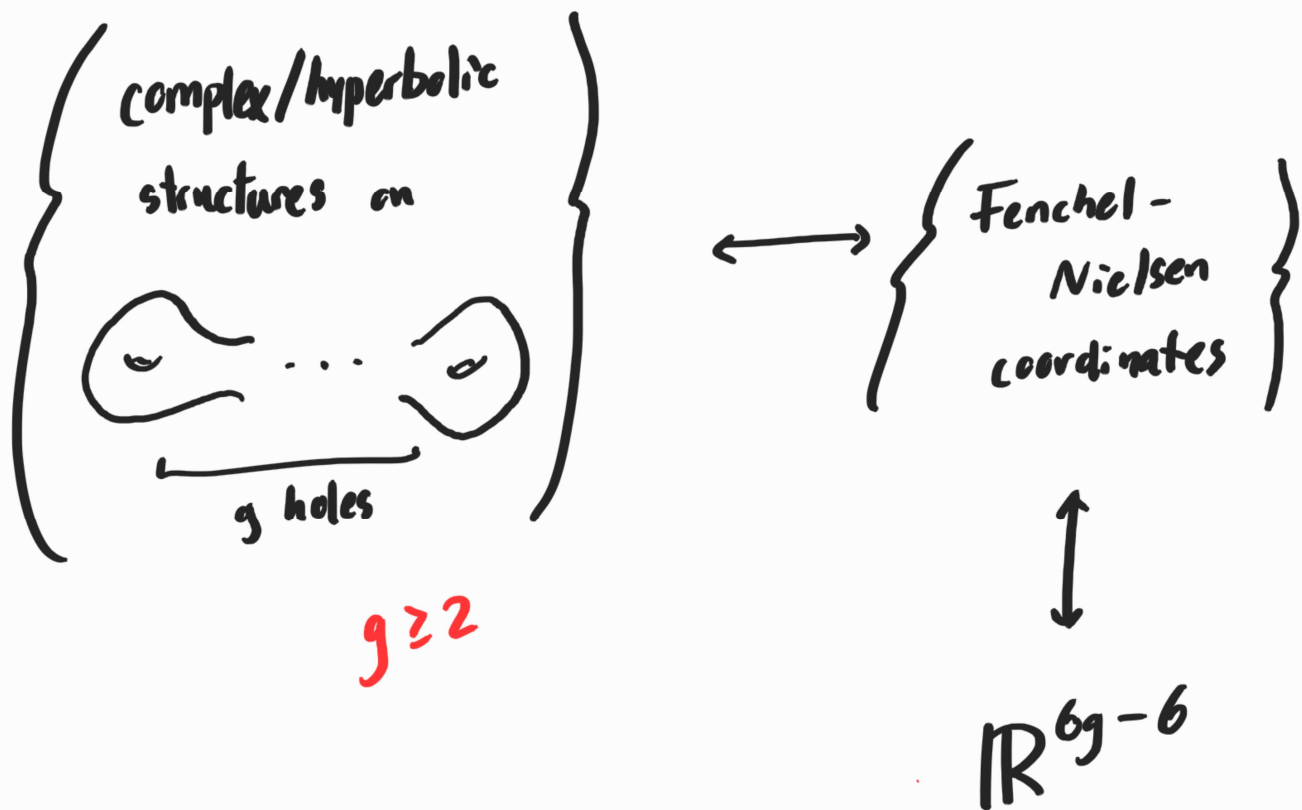
↕

{ points in
 $Gr(k, n)$ }

where $Gr(k, n) =$ Grassmannian manifold.

Here are some more complicated ones:

⑤ Complex/hyperbolic surfaces



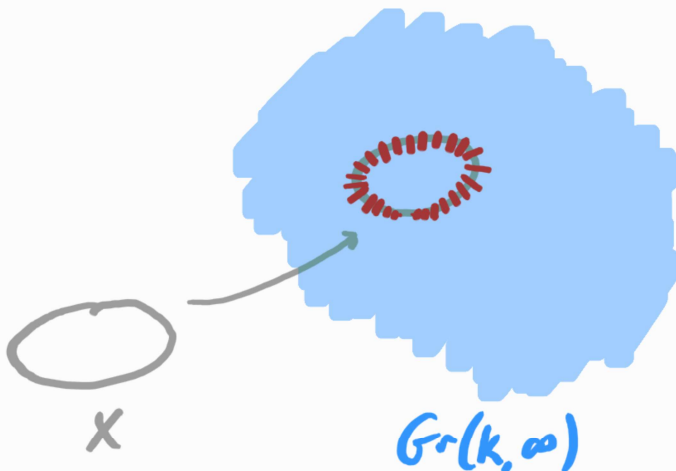
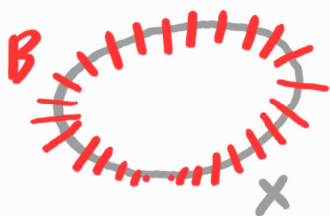
⑥ Vector bundles and G -bundles

(Rank k vector)

{ bundles on X
up to iso. }



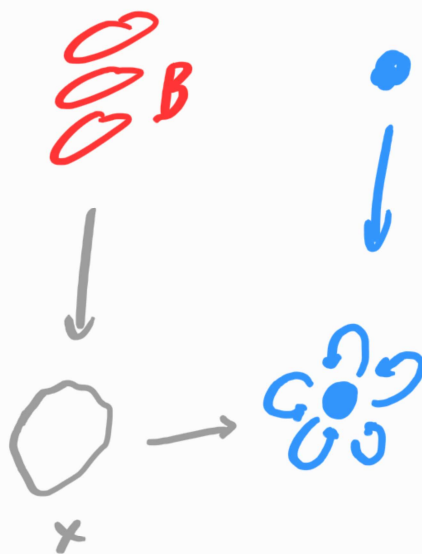
$Gr(k, \infty)$



{ principal
 G -bundles
up to iso. }



BG



Lines on Cubic Surfaces