

What is ...  
a Moduli Space?

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Begonia



Poppy

Today's lesson plan:



Individual  
objects



Points  
of a  
moduli space

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## Introduction

Loose definition: a moduli problem  
is a problem of the form

"classify all objects of a certain type"

usually + "up to isomorphism"

In many situations, the solutions to such problems can be parametrized geometrically — we can view the solutions themselves as points in some parameter space, called a **moduli space**.

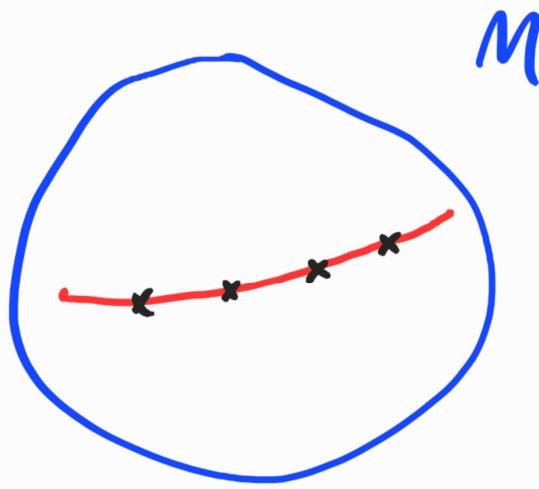


The utility of this is:

- if the space  $M$  has any extra structure (e.g. a metric, a group structure, the structure of a variety), then this sheds light on all solutions simultaneously,
- most powerfully, we can produce families of solutions by picking meaningful subsets of the moduli space.

sol'n  
sol'n  
sol'n  
sol'n

family of  
solutions  
parametrized  
by a curve



Here are some familiar examples:

① Circles in  $\mathbb{R}^2$

Every circle  $C \subseteq \mathbb{R}^2$  is uniquely

specified by \_\_\_\_\_.

A moduli space for circles in  $\mathbb{R}^2$

is

② Circles in  $\mathbb{R}^2$  up to isometry

Two circles  $C_1, C_2 \subseteq \mathbb{R}^2$  are  
isometric if they have the  
same size.

So circles up to isometry are  
classified by \_\_\_\_\_.

A moduli space for circles up  
to isometry is



### ③ Lines in $\mathbb{R}^2$

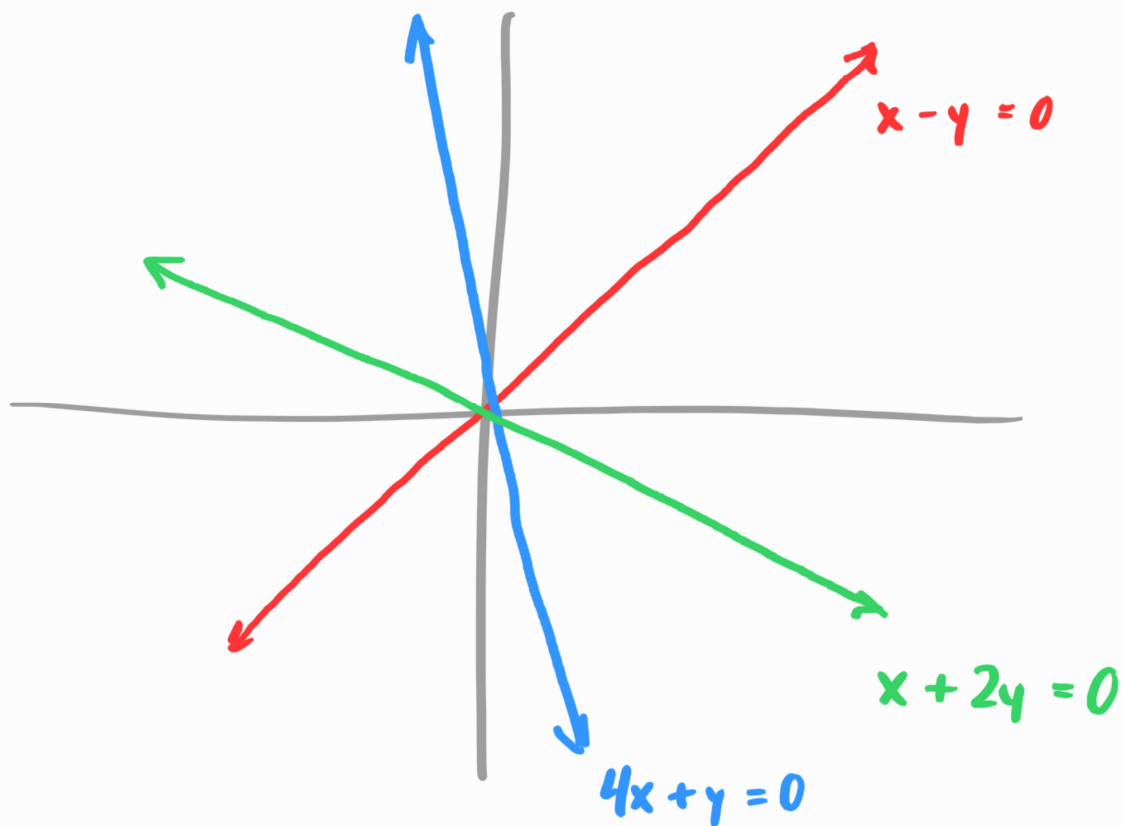
A line in  $\mathbb{R}^2$  is given by an equation  $ax + by = c$ , so we can think of

$$\{(a, b, c) \mid a, b, c \in \mathbb{R}\}.$$

BUT this misses when two equations represent the same line

$$\text{e.g. } (x + y = 1) \simeq (2x + 2y = 2)$$

To make things simpler, let's  
just consider lines through  $(0, 0)$ :



$$L: ax + by = 0$$

A line through the origin is

uniquely specified by

A moduli space of lines through  
the origin is

④ More generally,

$\left\{ \begin{array}{l} \text{lines through} \\ \vec{a} \text{ in } \mathbb{R}^n \end{array} \right\} \longleftrightarrow \left\{ \begin{array}{l} \text{unit vector} \\ \text{up to } \pm 1 \end{array} \right\}$

↕

{ points in  
 $\mathbb{P}^{n-1}$  }

where  $\mathbb{P}^{n-1} = S^{n-1} / \text{identify antipodes}$

Most generally,

{ k-dim'l subspaces  
in  $\mathbb{R}^n$  } ↔ { k-frame  
up to  
 $GL_k(\mathbb{R})$  }

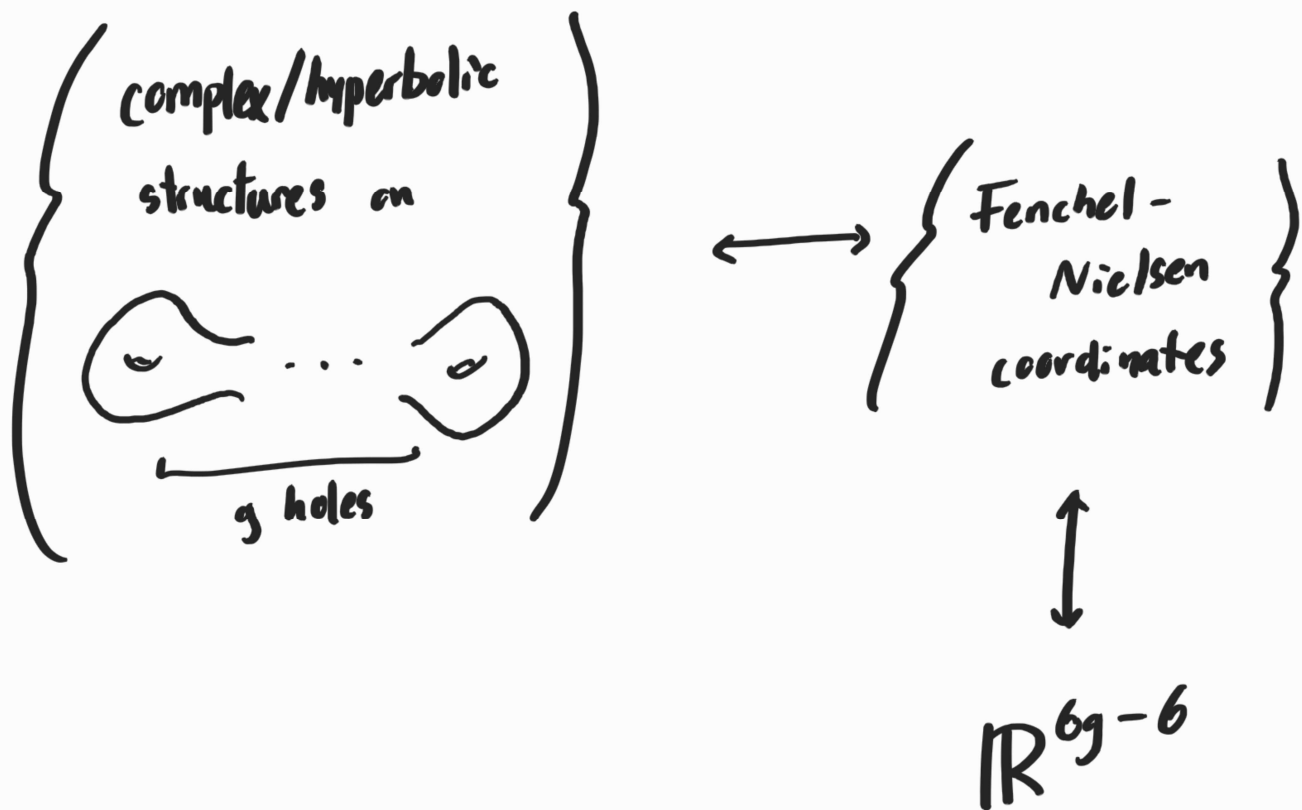
↕

{ points in  
 $Gr(k, n)$  }

where  $Gr(k, n) =$  Grassmannian manifold.

Here are some more complicated ones:

### ⑤ Complex/hyperbolic surfaces



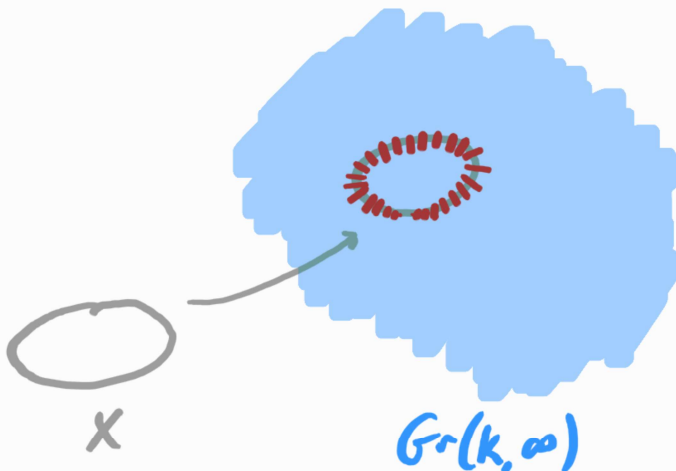
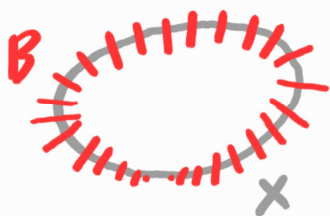
### ⑥ Vector bundles and $G$ -bundles

(Rank  $k$  vector)

{ bundles on  $X$   
up to iso. }



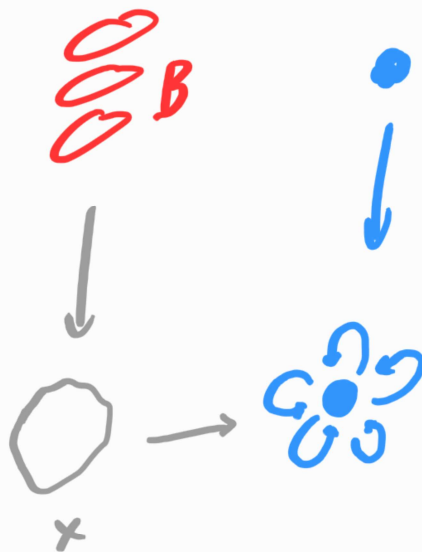
$Gr(k, \infty)$



{ principal  
 $G$ -bundles  
up to iso. }



$BG$



Lines on Cubic Surfaces